

**ΑΠΟΛΥΤΗΡΙΕΣ ΕΞΕΤΑΣΕΙΣ Δ΄ ΤΑΞΗΣ
ΕΣΠΕΡΙΝΟΥ ΓΕΝΙΚΟΥ ΛΥΚΕΙΟΥ
ΠΑΡΑΣΚΕΥΗ 23 ΜΑΪΟΥ 2008
ΑΠΑΝΤΗΣΕΙΣ ΣΤΗΝ ΗΛΕΚΤΡΟΛΟΓΙΑ ΤΕΧΝΟΛΟΓΙΚΗΣ
ΚΑΤΕΥΘΥΝΣΗΣ**

ΟΜΑΔΑ Α

A.1. β

A.2. α

A.3. δ

A.4. γ

A.5. α

A.6. α) Σ, β) Λ, γ) Σ, δ) Λ, ε) Σ.

A.7. 1^{ος} τρόπος

x	y	\bar{x}	\bar{y}	$x+\bar{y}$	$y+\bar{x}$	$x(y+\bar{x})$	$y(x+\bar{y})$	$x(y+\bar{x})+y(x+\bar{y})$	$\overline{x(y+\bar{x})+y(x+\bar{y})}$	$\bar{x}+\bar{y}$
0	0	1	1	1	1	0	0	0	1	1
0	1	1	0	0	1	0	0	0	1	1
1	0	0	1	1	0	0	0	0	1	1
1	1	0	0	1	1	1	1	1	0	0

2^{ος} τρόπος

$$\begin{aligned} \overline{x \cdot (y + \bar{x}) + y \cdot (x + \bar{y})} &= \overline{x \cdot (y + \bar{x})} \cdot \overline{y \cdot (x + \bar{y})} \\ &= (\bar{x} + \overline{(y + \bar{x})}) \cdot (\bar{y} + \overline{(x + \bar{y})}) \\ &= (\bar{x} + \bar{y} \cdot x) \cdot (\bar{y} + \bar{x} \cdot y) \\ &= (\bar{x} + \bar{y})(\bar{x} + x) \cdot (\bar{y} + \bar{x})(\bar{y} + y) \\ &= (\bar{x} + \bar{y}) \cdot (\bar{y} + \bar{x}) = \bar{x} + \bar{y} \end{aligned}$$

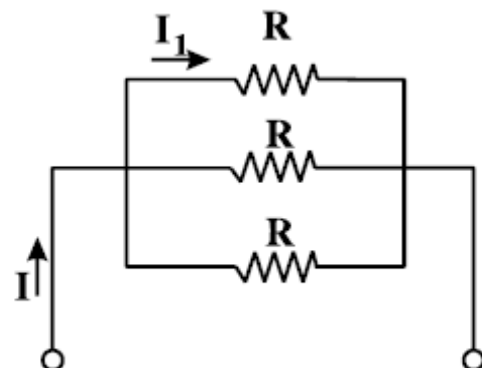
ΟΜΑΔΑ Β

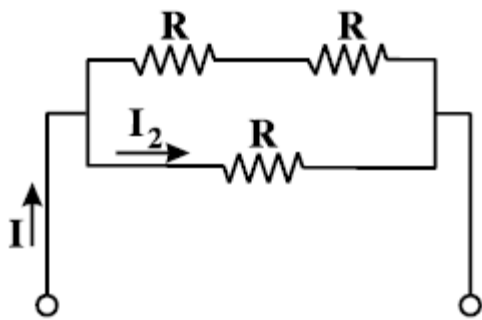
B.1.

$$R_{\text{ολ}} = \frac{R}{3}$$

$$\left. \begin{aligned} V_1 &= I \cdot R_{\text{ολ}} \\ V_1 &= I_1 \cdot R \end{aligned} \right\} \text{άρα } I \cdot R_{\text{ολ}} = I_1 \cdot R \Leftrightarrow$$

$$I \cdot \frac{R}{3} = I_1 \cdot R \Leftrightarrow I_1 = \frac{I}{3}$$





$$R_{o\lambda} = \frac{2R \cdot R}{2R + R} = \frac{2R}{3}$$

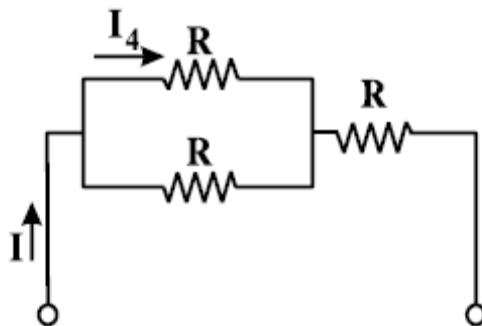
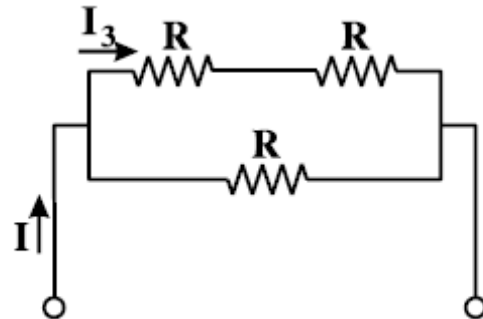
$$\left. \begin{array}{l} V_2 = I \cdot R_{o\lambda} \\ V_2 = I_2 \cdot R \end{array} \right\} \text{ \acute{\alpha}\rho\alpha } I \cdot R_{o\lambda} = I_2 \cdot R \Leftrightarrow$$

$$I \cdot \frac{2R}{3} = I_2 \cdot R \Leftrightarrow I_2 = \frac{2I}{3}$$

$$R_{o\lambda} = \frac{I \cdot 2R \cdot R}{2R + R} = \frac{2R}{3}$$

$$\left. \begin{array}{l} V_3 = I \cdot R_{o\lambda} \\ V_3 = I_3 \cdot 2R \end{array} \right\} \text{ \acute{\alpha}\rho\alpha } I \cdot R_{o\lambda} = I_3 \cdot 2R \Leftrightarrow$$

$$I \cdot \frac{2R}{3} = I_3 \cdot 2R \Leftrightarrow I_3 = \frac{I}{3}$$



$$\left. \begin{array}{l} V_4 = I \cdot \frac{R}{2} \\ V_4 = I_4 \cdot R \end{array} \right\} \text{ \acute{\alpha}\rho\alpha }$$

$$I \cdot \frac{R}{2} = I_4 \cdot R \Leftrightarrow I_4 = \frac{I}{2}$$

$$\text{\acute{\A}}\rho\alpha I_1 = I_3.$$

B.2.

$$\omega = 100 \text{ rad/sec} \quad \varphi_0 = 0^\circ$$

$$\alpha) X_L = \omega L = 100 \cdot 0,03 = 3\Omega$$

$$\beta) Z = \sqrt{R^2 + X_L^2} = \sqrt{3^2 + 3^2} = 3\sqrt{2} \Omega$$

$$\gamma) \varphi_Z = \text{τοξεφ} \frac{X_L}{R} = \text{τοξεφ} \frac{3}{3} = \text{τοξεφ} 1 = \frac{\pi}{4}$$

$$\delta) i = \frac{V_0}{Z} \cdot \eta\mu(\omega t + \varphi_0 - \varphi_Z) = \frac{300}{3\sqrt{2}} \cdot \eta\mu\left(100t - \frac{\pi}{4}\right)$$

$$\epsilon) P = V_{\text{EV}} \cdot I_{\text{EV}} \cos\varphi_Z = \frac{1}{2} \cdot V_0 \cdot I_0 \cos\frac{\pi}{4} = \frac{1}{2} \cdot 300 \cdot 50\sqrt{2} \frac{\sqrt{2}}{2} = 7500 \text{ W}$$

$$\sigma\tau) S = V_{\text{EV}} \cdot I_{\text{EV}} = \frac{1}{2} \cdot V_0 \cdot I_0 = \frac{1}{2} \cdot 300 \cdot 50\sqrt{2} = 7500\sqrt{2} \text{ VA}$$